

WHAT IS CLAIMED IS:

1. A remotely controlled vehicle system, comprising:

5 a remote control signal transmitter for

transmitting control signals;

a master model vehicle containing a remote control signal receiver, wherein said master model vehicle is controlled by said control signals as it travels along a first pathway;

10 at least one slave model vehicle that is coupled

to said master model vehicle and is propelled by said master model vehicle in a pathway outside of said first pathway.

15 2. The system according to Claim 1, wherein said at

least one slave model vehicle is oriented in a

formation with said master model vehicle, wherein

said at least one slave model vehicle and said master model vehicle move in different pathways while

20 remaining in said formation.

3. The system according to Claim 2, wherein said

formation is selectively adjustable by said remote

control transmitter.

4. The system according to Claim 1, wherein said
at least one slave vehicle is coupled to said master
vehicle by at least one linkage element that extends
5 from said master model vehicle at a predetermined
angle.

5. The system according to Claim 4, wherein said
master model vehicle contains a servo motor that is
10 controlled by said remote control transmitter that
selectively adjusts said predetermined angle.

6. The system according to Claim 1, having
multiple slave model vehicles, wherein some of said
15 slave model vehicles are interconnected by secondary
linkage elements that are not coupled to said master
model vehicle.

7. The system according to Claim 1, wherein said
20 master model vehicle and said at least one slave
model vehicle are selected from a group consisting of
cars, trucks, airplanes, boats and robots.

8. A method of moving a plurality of model vehicles in formation, comprising the steps of:

5 providing a motor and a control system in a first of said model vehicles, wherein said first of said model vehicles travels along a first pathway;

10 coupling a remainder of said plurality of model vehicles to said first of said model vehicles, wherein said remainder of said plurality of model vehicles are moved in a formation by said first of said model vehicles along at least one pathway that is adjacent said first pathway.

15 9. The method according to Claim 8, further including the step of selectively adjusting said formation as said remainder of said plurality of model vehicle are moved by said first of said model vehicles.

20 10. The method according to Claim 8, wherein said step of providing a motor and a control system in a first of said model vehicles includes providing a remotely controlled model vehicle.

11. The method according to Claim 8, wherein said
step of coupling a remainder of said plurality of
model vehicles to said first of said model vehicles
includes coupling at least some of said remainder of
5 said plurality of model vehicles to said first of
said model vehicles with at least one linkage.

12. An assembly, comprising:
10 a remotely controlled vehicle that moves along a
first pathway as directed by remote control signals;
and
15 at least one secondary vehicle coupled to said
remotely controlled vehicle that is moved in
formation by said remotely controlled vehicle along
at least one pathway adjacent said first pathway.

13. The assembly according to Claim 12, wherein said
remotely controlled vehicle is coupled to said at
least one secondary vehicle by at least one linkage
20 element that extends from said remotely controlled
vehicle at a predetermined angle.

14. The assembly according to Claim 13, wherein said predetermined angle can be selectively adjusted by remote control.

5 15. The assembly according to Claim 12, wherein said remotely controlled vehicle is a car and said at least one secondary vehicle is a car having generally the same shape and appearance as said remotely controlled vehicle.